# Path Detection: A Quantum Computing Primitive

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Based on work with Stacey Jeffery: arXiv: 1704.00765 (Quantum vol 1 p 26) Michael Jarret, Stacey Jeffery, Alvaro Piedrafita, *in progress* 



Middlebury

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  - 2. Easy to understand and analyze (without knowing quantum mechanics)

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- New primitive: *st*-connectivity

### **Outline:**

- A. Introduction to st-connectivity
- B. st-connectivity makes a good algorithmic primitive
  - I. Applies to a wide range of problems

2. Easy to understand (without knowing quantum mechanics)C. Applications and performance of algorithm

#### st-connectivity

st - connectivity: is there a path from s to t?



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### **Black Box Model**



Let  $\mathcal{H}$  be the set of graphs G that the black box might contain.



# **Figure of Merit**

- Query Complexity
  - Number of uses (queries) of the black box
  - All other operations are free
- Under mild assumption, for our algorithm, quantum query complexity  $\cong$  quantum time complexity

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### **Boolean Formulas**



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# **Boolean Formula Applications**

- Logic
- Designing electrical circuits
- Game theory (deciding who will win a game)
- Combinatorics and graph problems
- Linear programming
- Testing potential solution to an NP-complete problem

AND: outputs 1 if all input subformulas have value 1

S

t

s and t are connected if all subgraphs are connected

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OR: outputs 1 if any input subformulas have value 1 s and t are connected if any subgraph is t connected









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# **Effective Resistance** 1 unit resistors S S $R_{s,t}(G)$ unit resistor t t





Valid flow:

- 1 unit in at s
- 1 unit out at t
- At all other nodes, zero net flow













![](_page_35_Figure_0.jpeg)

Valid potential energy:

- 1 at *s*
- 0 at *t*
- Potential energy difference is 0 across edge

![](_page_36_Figure_5.jpeg)

Valid potential energy:

- 1 at *s*
- 0 at *t*
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![](_page_37_Figure_5.jpeg)

Cut energy:

 $\sum_{edges} (Potential \, Energy \, Difference)^2$ 

Effective Capacitance:  $C_{s,t}(G')$ Smallest cut energy of any valid potential energy between s to t on G'.

![](_page_38_Figure_4.jpeg)

### **Algorithm Performance:**

st-connectivity algorithm complexity =

$$O\left(\sqrt{\max_{G\in\mathcal{H}:connected}R_{s,t}(G)}\sqrt{\max_{G'\in\mathcal{H}:not\ connected}C_{s,t}(G')}\right)$$

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[Belovs, Reichard, '12]

[JJKP, in progress]

What is quantum complexity of deciding  $AND(x_1, x_2, ..., x_N)$ , promised

- All  $x_i = 1$ , or
- At least  $\sqrt{N}$  input variables are 0.

![](_page_42_Picture_1.jpeg)

What is quantum complexity of deciding  $AND(x_1, x_2, ..., x_N)$ , promised

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What is quantum complexity of deciding if

- s and t are connected, or
- At least  $\sqrt{N}$  edges are missing

![](_page_43_Picture_1.jpeg)

What is quantum complexity of deciding if

- *s* and *t* are connected, or
- At least  $\sqrt{N}$  edges are missing

 $\max_{G \in \mathcal{H}: connected} R_{s,t}(G) \sqrt{\max_{G' \in \mathcal{H}: not \ connected} C_{s,t}(G')}$ 

![](_page_44_Figure_1.jpeg)

![](_page_45_Picture_1.jpeg)

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![](_page_46_Picture_1.jpeg)

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![](_page_47_Figure_1.jpeg)

![](_page_48_Figure_1.jpeg)

![](_page_49_Figure_1.jpeg)

What is quantum complexity of deciding if

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![](_page_49_Figure_5.jpeg)

Quantum complexity is  $O(N^{1/4})$ 

![](_page_50_Figure_1.jpeg)

What is quantum complexity of deciding if

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![](_page_50_Figure_5.jpeg)

Quantum complexity is  $O(N^{1/4})$ 

Randomized classical complexity is  $\Omega(N^{1/2})$ 

Connectivity – is every vertex connected to every other vertex?

![](_page_51_Figure_2.jpeg)

Connectivity – is every vertex connected to every other vertex?

Connectivity=  $(st - conn) \land (su - conn) \land (uv - conn) \dots$ 

![](_page_52_Figure_3.jpeg)

Connectivity – is every vertex connected to every other vertex?

Connectivity=  $(st - conn) \land (su - conn) \land (uv - conn) \dots$ 

![](_page_53_Picture_3.jpeg)

Connectivity – is every vertex connected to every other vertex?

Results:

- Worst case:  $O(n^{3/2})$  (n = # vertices)
- Promised
  - YES diameter is D
  - NO every connected component has at most n<sup>\*</sup> vertices
  - $O(\sqrt{nn^*D})$

![](_page_54_Picture_8.jpeg)

Connectivity – is every vertex connected to every other vertex?

Results:

- Worst case:  $O(n^{3/2})$  (n = # vertices)
- Promised
  - YES diameter is D
  - NO every connected component has at most *K* vertices
  - $O(\sqrt{nKD})$

(Diameter result previously discovered by Arins using slightly different approach)

![](_page_55_Picture_9.jpeg)

Span Program

- Span vectors
- Target vector

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Thus span program encodes a function.

Infinite number of span programs can encode the same function

Given a span program, can create a quantum algorithm to evaluate the corresponding function (create a quantum walk whose dispersion operators are based on the vectors)

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The efficiency of the span program is a (relatively) simple function of the vectors.

There is always a span program algorithm that is optimal (and many that are not optimal.)

#### **Open Questions and Current Directions**

- When is our algorithm optimal for Boolean formulas? (Especially partial/read-many formulas)
- Are there other problems that reduce to st-connectivity? (Perhaps all?)
- What is the classical time/query complexity of st-connectivity in the black box model? Under the promise of small capacitance/resistance?
- Does our reduction from formulas to connectivity give good classical algorithms too?
- How to choose weights?